

# 9-36V ProLynx 3A: Non-Isolated DC-DC Power Modules

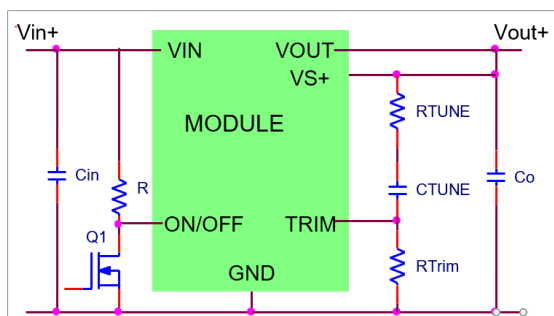
9Vdc – 36Vdc input; 3Vdc to 18Vdc output; 3A to 1.5A Scaled output current



RoHS Compliant

## Applications

- Industrial equipment
- Distributed power architectures
- Intermediate bus voltage applications
- Telecommunications equipment



## Features

- Compliant to RoHS Directive 2011/65/EU and amended Directive (EU) 2015/863
- Compliant to REACH Directive (EC) No 1907/2006
- Compatible in a Pb-free or SnPb reflow environment (Z versions)
- Extra Wide Input voltage range (9Vdc–36Vdc)
- Output voltage programmable from 3Vdc to 18 Vdc via external resistor
- Tunable Loop™ to optimize dynamic output voltage response
- Patent Pending AutoLimit automatic scaling of current limit with output voltage
- Output overcurrent protection (non-latching)
- Overtemperature protection
- Remote On/Off
- Remote Sense
- Small size: 20.3 mm x 11.4 mm x 8.5 mm (0.8 in x 0.45 in x 0.335 in)
- Wide operating temperature range (-40°C to 85°C)
- ANSI/UL\* 62368-1 and CAN/CSA† C22.2 No. 62368-1 Recognized, DIN VDE‡ 0868-1/A11:2017 (EN62368-1:2014/A11:2017)
- ISO\*\* 9001 and ISO 14001 certified manufacturing facilities

(See footnotes on the last page.)

## Technical Specifications

### Absolute Maximum Ratings

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage: Continuous	All	$V_{IN}$	-0.3	37	Vdc
Operating Ambient Temperature (see thermal considerations section)	All	$T_A$	-40	85	°C
Storage Temperature	All	$T_{stg}$	-55	125	°C

### Electrical Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

Parameter	Device	Symbol	Min	Typ	Max	Unit
Operating Input Voltage	All	$V_{IN}$	9	—	36	Vdc
Maximum Input Current ( $V_{IN}=9V$ to $36V$ , $I_O=I_{O,max}$ )	All	$I_{IN,max}$			2	A
Input No Load Current ( $V_{IN} = 28V$ , $I_O = 0$ , module enabled) ( $V_{IN} = 28V$ , $I_O = 0$ , module enabled)	$V_{O,set} = 3Vdc$ $V_{O,set} = 18Vdc$	$I_{IN,No\ load}$ $I_{IN,No\ load}$		22 54		mA mA
Input Stand-by Current ( $V_{IN} = 28Vdc$ , module disabled)	All	$I_{IN,stand-by}$		1.3		mA
Inrush Transient	All	$I^2t$		0.5		A <sup>2</sup> s
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, 1 $\mu$ H source impedance; $V_{IN} = 0$ to 36V, $I_O = I_{O,max}$ ; See Test Configurations)	All			25		mAp-p
Input Ripple Rejection (120Hz)	All		-41	-54	-69	dB

#### CAUTION: This power module is not internally fused. An input line fuse must always be used.

This power module can be used in a wide variety of applications, ranging from simple standalone operation to an integrated part of sophisticated power architecture. To preserve maximum flexibility, internal fusing is not included; however, to achieve maximum safety and system protection, always use an input line fuse. The safety agencies require a fast-acting fuse with a maximum rating of 8 A (see Safety Considerations section). Based on the information provided in this data sheet on inrush energy and maximum dc input current, the same type of fuse with a lower rating can be used. Refer to the fuse manufacturer's data sheet for further information.

Output Voltage Set-point	All	$V_{O,set}$	-2	—	+2	% $V_{O,set}$
Output Voltage (Over all operating input voltage, resistive load, and temperature conditions until end of life)	All	$V_{O,set}$	-2.5	—	+2.5	% $V_{O,set}$
Adjustment Range (elected by an external resistor) (Some output voltages may not be possible depending on the input voltage – see Feature Descriptions Section)	All	$V_O$	3		18	Vdc
Output Regulation Line ( $V_{IN}=V_{IN,min}$ to $V_{IN,max}$ )	All			—	0.4	% $V_{O,set}$
Load ( $I_O=I_{O,min}$ to $I_{O,max}$ )	All			—	0.4	% $V_{O,set}$
Temperature ( $T_{ref}=T_{A,min}$ to $T_{A,max}$ )	All			—	0.4	% $V_{O,set}$
Remote Sense Range	All				0.5	Vdc

## Technical Specifications

### Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Typ	Max	Unit
Output Ripple and Noise on nominal output ( $V_{IN}=V_{IN,nom}$ and $I_O=I_{O,min}$ to $I_{O,max}$ $C_O = 0.1\mu F // 10 \mu F$ ceramic capacitors) $V_{out}=3.3V$ , $V_{in}=28V$						
Peak-to-Peak (5Hz to 20MHz bandwidth)	All			38		$mV_{pk-pk}$
RMS (5Hz to 20MHz bandwidth)	All			12		$mV_{rms}$
$V_{out}=18V$ , $V_{in}=28V$						
Peak-to-Peak (5Hz to 20MHz bandwidth)	All			116		$mV_{pk-pk}$
RMS (5Hz to 20MHz bandwidth)	All			38		$mV_{rms}$
External Capacitance <sup>1</sup> Without the Tunable Loop™						
ESR $\geq 1 m\Omega$	All	$C_{O,max}$	0	—	47	$\mu F$
ESR $\geq 10 m\Omega$	All	$C_{O,max}$	0	—	100	$\mu F$
With the Tunable Loop™						
ESR $\geq 0.15 m\Omega$	All	$C_{O,max}$	0	—	100	$\mu F$
ESR $\geq 10 m\Omega$	All	$C_{O,max}$	0	—	2000*	$\mu F$
Output Current						
$V_O=3V$			0		3	
$V_O=5V$	All	$I_O$	0		2.5	A <sub>dc</sub>
$V_O=12V$			0		2	
$V_O=18V$			0		1.5	
Output Current Limit Inception (Hiccup Mode)	All	$I_{O,lim}$		200		% $I_{O,max}$
Output Short-Circuit Current ( $V_O \leq 250mV$ ) (Hiccup Mode)	All	$I_{O,s/c}$		1		A <sub>rms</sub>
Efficiency ( $I_O=I_{O,max}$ , $V_O=V_{O,set}$ )						
$V_{IN}=12Vdc$ , $T_A=25^\circ C$	$V_{O,set} = 3.3Vdc$	$\eta$		93.2		%
$V_{IN}=12Vdc$ , $T_A=25^\circ C$	$V_{O,set} = 5Vdc$	$\eta$		95.5		%
$V_{IN}=28Vdc$ , $T_A=25^\circ C$	$V_{O,set} = 12Vdc$	$\eta$		96.0		%
$V_{IN}=28Vdc$ , $T_A=25^\circ C$	$V_{O,set} = 18Vdc$	$\eta$		97.0		%
Switching Frequency	All	$f_{sw}$	—	300	—	kHz

### General Specifications

Parameter	Min	Typ	Max	Unit
Calculated MTBF ( $I_O=0.8I_{O,max}$ , $T_A=40^\circ C$ ) Telcordia Issue 2 Method 1 Case 3		18,014,158		Hours
Weight	—	3.5 (0.123)	—	g (oz.)

### Feature Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Typ	Max	Unit
On/Off Signal Interface ( $V_{IN}=V_{IN,min}$ to $V_{IN,max}$ ; open collector or equivalent, Signal referenced to GND)						
Device is with suffix "4" – Positive Logic (See Ordering Information)						
Logic High (Module ON)						
Input High Current	All	$I_{IH}$	—	—	160	$\mu A$
Input High Voltage	All	$V_{IH}$	4.2	—	12	V
Logic Low (Module OFF)						
Input Low Current	All	$I_{IL}$	—	—	0.5	mA
Input Low Voltage	All	$V_{IL}$	-0.3	—	3.3	V

# Technical Specifications (continued)

## Feature Specifications (continued)

Parameter	Device	Symbol	Min	Typ	Max	Unit
Device Code with no suffix – Negative Logic (See Ordering Information)						
Logic High (Module OFF)						
Input High Current	All	$I_{IH}$	—	—	3	mA
Input High Voltage	All	$V_{IH}$	1.5	—	36	Vdc
Logic Low (Module ON)						
Input low Current	All	$I_{IL}$	—	—	220	$\mu$ A
Input Low Voltage	All	$V_{IL}$	-0.2	—	1	Vdc
Turn-On Delay and Rise Times						
( $V_{IN}=V_{IN,nom}$ , $I_O=I_{O,max}$ , $V_O$ to within $\pm 1\%$ of steady state)						
Case 1: On/Off input is enabled and then input power is applied (delay from instant at which $V_{IN} = V_{IN,min}$ until $V_O = 10\%$ of $V_{O,set}$ )	All	Tdelay	—	12	—	msec
Case 2: Input power is applied for at least one second and then the On/Off input is enabled (delay from instant at which Von/Off is enabled until $V_O = 10\%$ of $V_{O,set}$ )	All	Tdelay	—	11	—	msec
Output voltage Rise time (time for $V_O$ to rise from 10% of $V_{O,set}$ to 90% of $V_{O,set}$ )	All	Trise	—	19	—	msec
Output voltage overshoot ( $T_A = 25^\circ\text{C}$ $V_{IN}=V_{IN,min}$ to $V_{IN,max}$ , $I_O = I_{O,min}$ to $I_{O,max}$ ) With or without maximum external capacitance					3	% $V_{O,set}$
Over Temperature Protection (See Thermal Considerations section)	All	$T_{ref}$		130		$^\circ\text{C}$
Input Undervoltage Lockout						
Turn-on Threshold	All				8.45	Vdc
Turn-off Threshold	All				8.25	Vdc
Hysteresis	All			0.2		Vdc

## Characteristic Curves

The following figures provide typical characteristics for the 9-36V ProLynx 3A at 3.3V<sub>o</sub> and at 25°C.

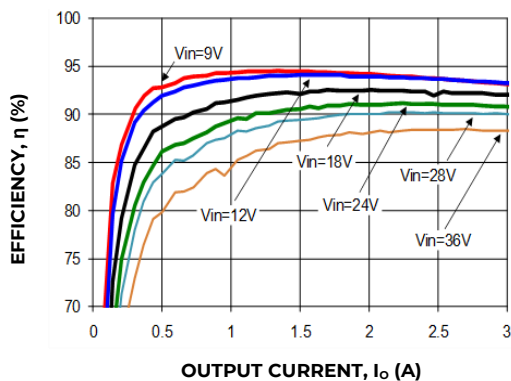


Figure 1. Converter Efficiency versus Output Current.

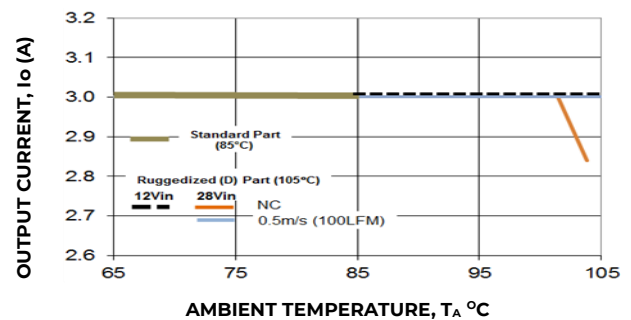


Figure 2. Derating Output Current versus Ambient Temperature and Airflow.

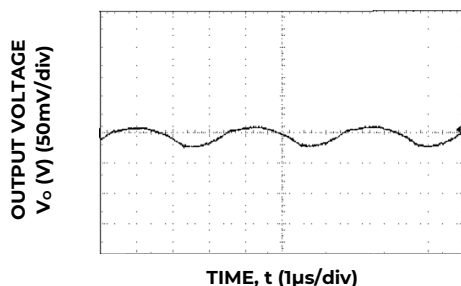


Figure 3. Typical output ripple and noise ( $V_{IN} = 18\text{V}$ ,  $I_O = I_{O,max}$ ).

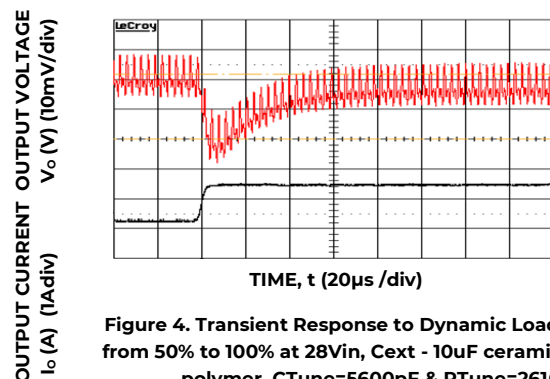


Figure 4. Transient Response to Dynamic Load Change from 50% to 100% at 28Vin, Cext - 10uF ceramic + 330uF polymer, CTune=5600pF & RTune=261Ω

# Technical Specifications (continued)

## Characteristic Curves (continued)

The following figures provide typical characteristics for the 9-36V ProLynx 3A at 5 Vo and at 25°C.

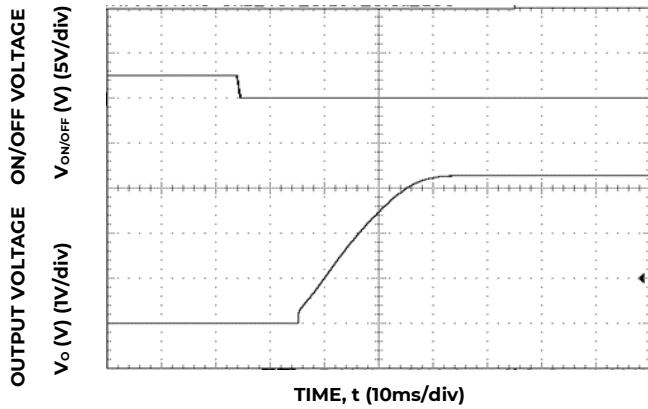


Figure 5. Typical Start-up Using On/Off Voltage ( $I_o = I_{o,max}$ ).

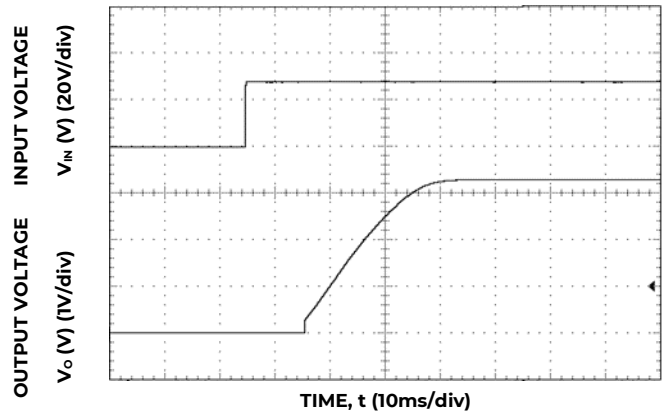


Figure 6. Typical Start-up Using Input Voltage ( $V_{IN} = 28V, I_o = I_{o,max}$ ).

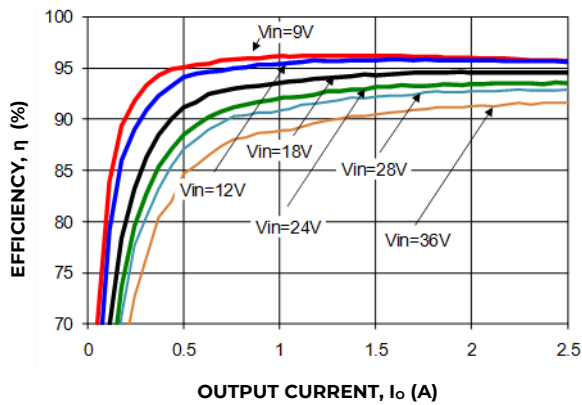


Figure 7. Converter Efficiency versus Output Current.

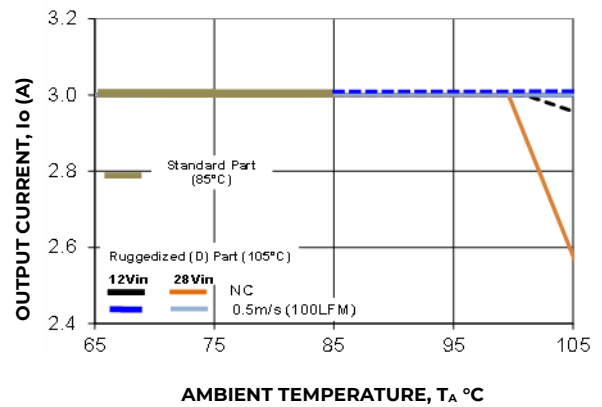


Figure 8. Derating Output Current versus Ambient Temperature and Airflow.

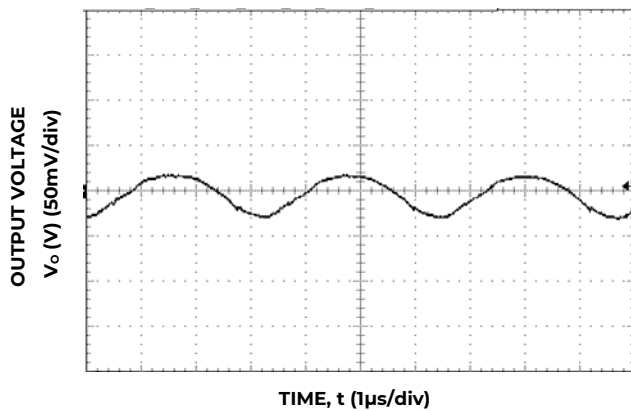


Figure 9. Typical output ripple and noise ( $V_{IN} = 18V, I_o = I_{o,max}$ ).

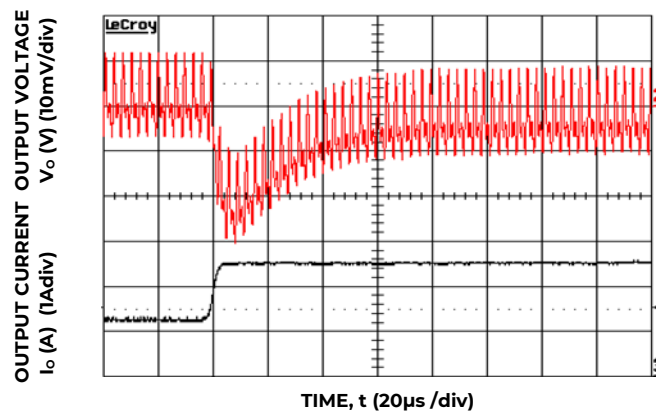


Figure 10. Transient Response to Dynamic Load Change from 50% to 100% at 28Vin, Cext - 10uF ceramic + 330uF polymer, CTune=5600pF & RTune=261Ω

# Technical Specifications (continued)

## Characteristic Curves (continued)

The following figures provide typical characteristics for the 9-36V ProLynx 3A at 12Vo and at 25°C.

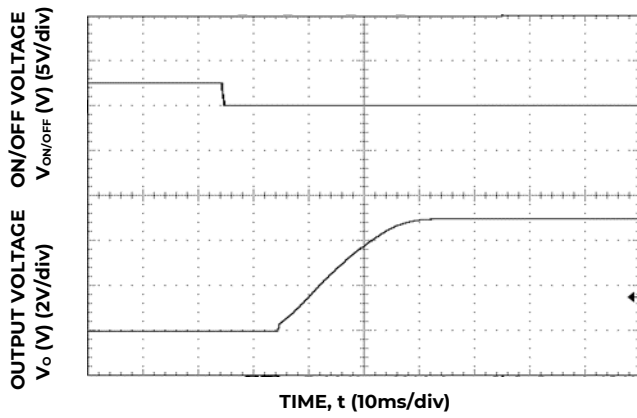


Figure 11. Typical Start-up Using On/Off Voltage ( $I_o = I_{o,max}$ ).

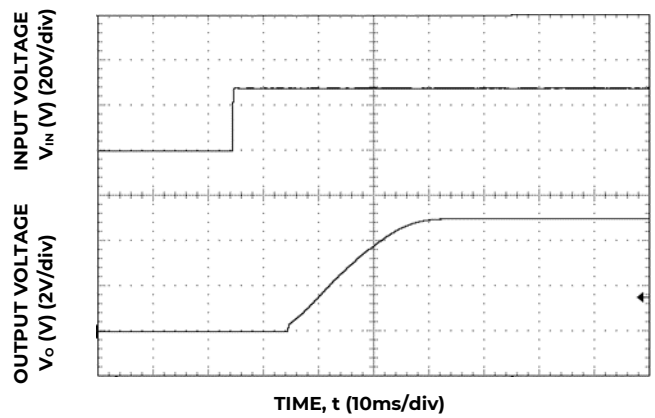


Figure 12. Typical Start-up Using Input Voltage ( $V_{IN} = 28V, I_o = I_{o,max}$ ).

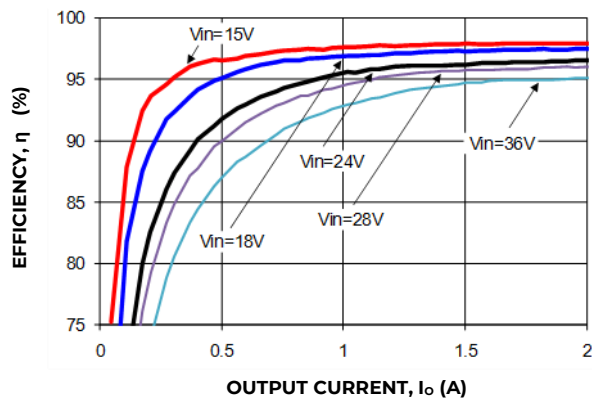


Figure 13. Converter Efficiency versus Output Current.

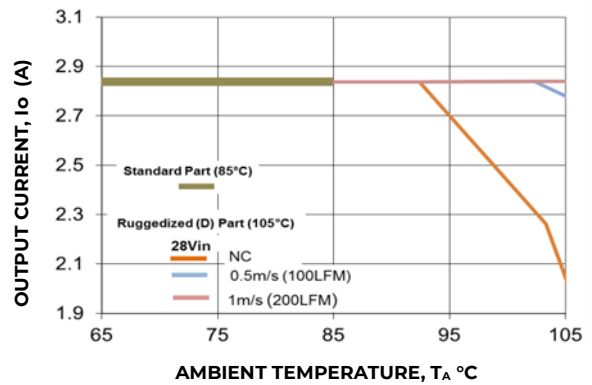


Figure 14. Derating Output Current versus Ambient Temperature and Airflow.

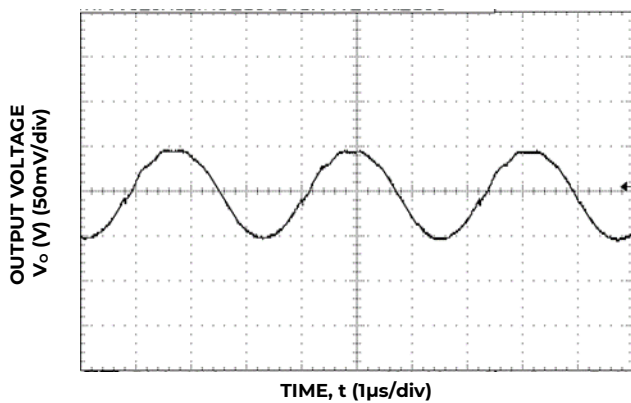


Figure 15. Typical output ripple and noise ( $V_{IN} = 28V, I_o = I_{o,max}$ ).

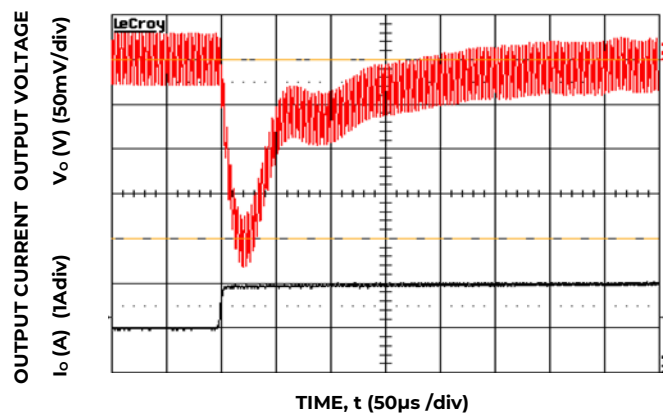


Figure 16. Transient Response to Dynamic Load Change from 50% to 100% at 28Vin,  $C_{ext} = 3 \times 10\mu F$  ceramic,  $C_{Tune} = 47pF$  &  $R_{Tune} = 332\Omega$

# Technical Specifications (continued)

## Characteristic Curves (continued)

The following figures provide typical characteristics for the 9-36V ProLynx 3A at 18Vo and at 25°C.

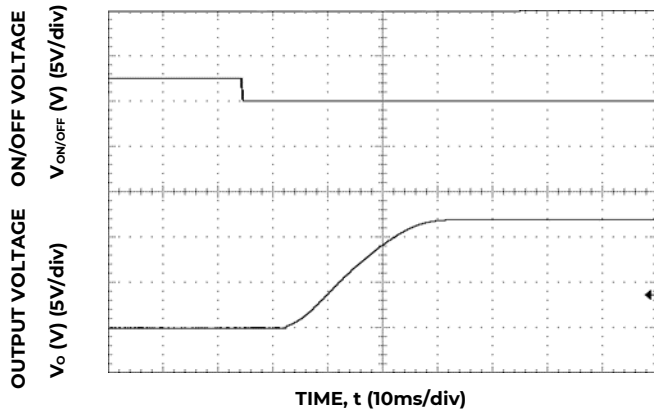


Figure 17. Typical Start-up Using On/Off Voltage ( $I_o = I_{o,max}$ ).

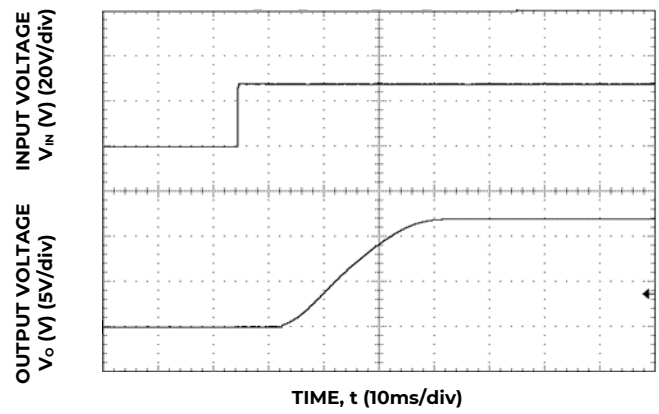


Figure 18. Typical Start-up Using Input Voltage ( $V_{IN} = 28V, I_o = I_{o,max}$ ).

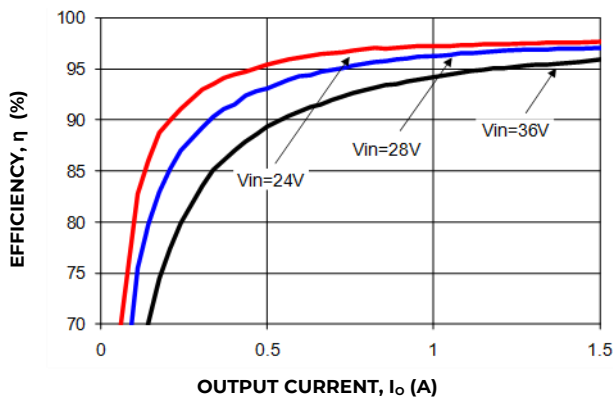


Figure 19. Converter Efficiency versus Output Current.

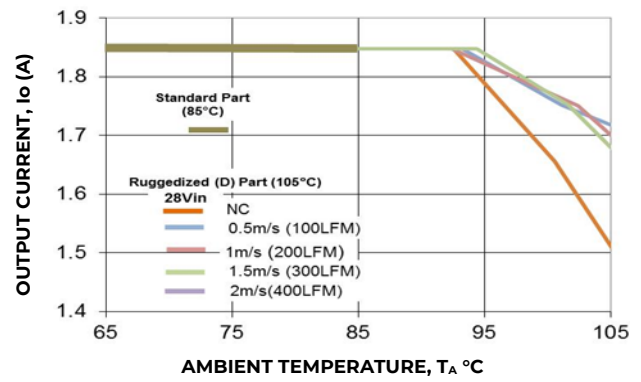


Figure 20. Derating Output Current versus Ambient Temperature and Airflow.

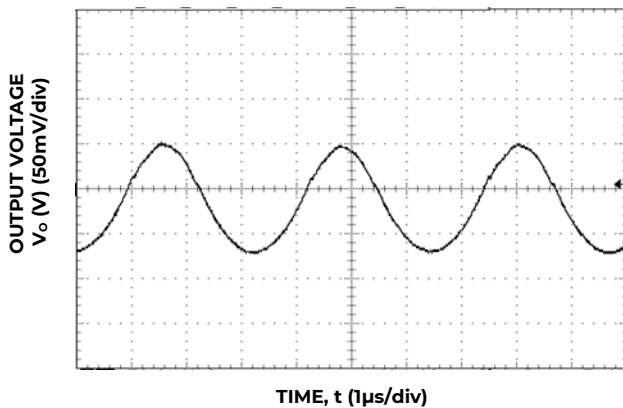


Figure 21. Typical output ripple and noise ( $V_{IN} = 28V, I_o = I_{o,max}$ ).

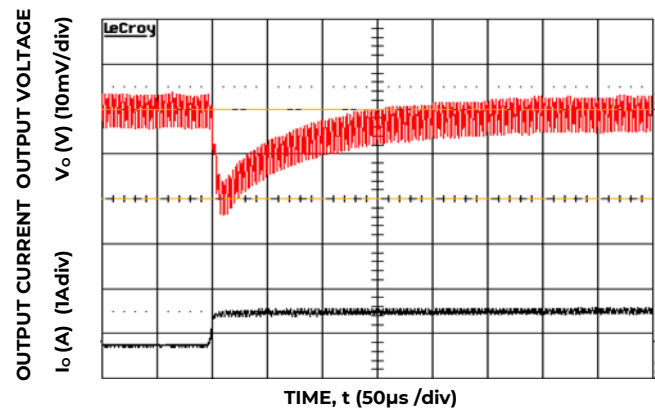
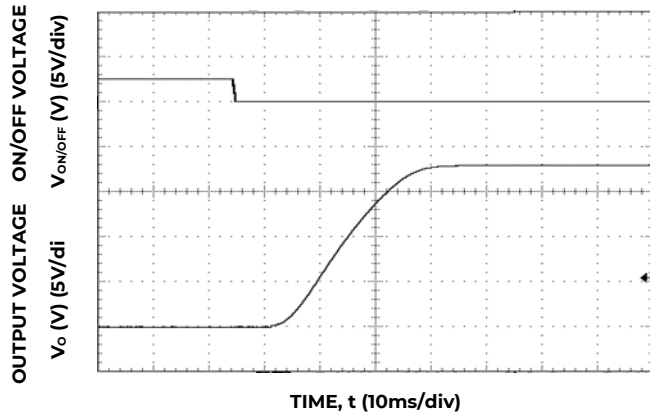


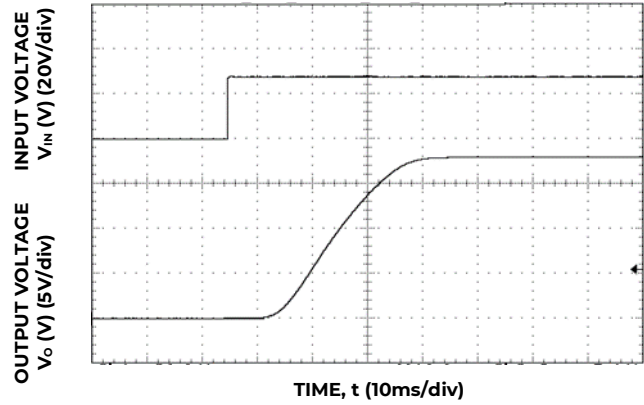
Figure 22. Transient Response to Dynamic Load Change from 50% to 100% at 28Vin, Cext - 1x10uF ceramic CTune=Open & RTune=Open

# Technical Specifications (continued)

## Characteristic Curves (continued)

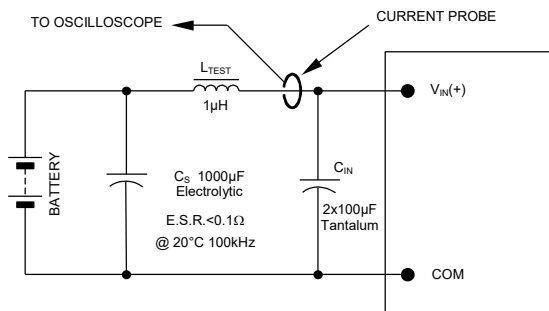


**Figure 23. Typical Start-up Using On/Off Voltage**  
( $I_o = I_{o,max}$ ).



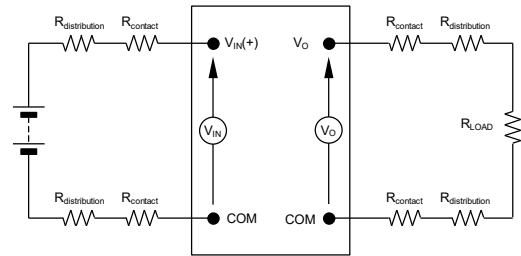
**Figure 24. Typical Start-up Using Input Voltage**  
( $V_{IN} = 28V, I_o = I_{o,max}$ ).

## Test Configurations



NOTE: Measure input reflected ripple current with a simulated source inductance ( $L_{TEST}$ ) of  $1\mu H$ . Capacitor  $C_S$  offsets possible battery impedance. Measure current as shown above.

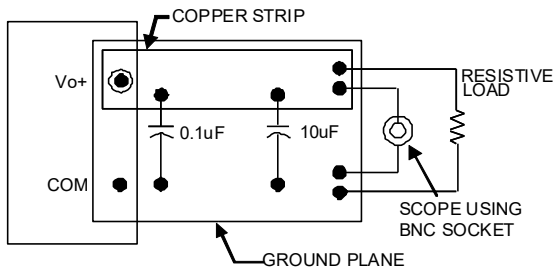
**Figure 25. Input Reflected Ripple Current Test Setup.**



NOTE: All voltage measurements to be taken at the module terminals, as shown above. If sockets are used then Kelvin connections are required at the module terminals to avoid measurement errors due to socket contact resistance.

**Figure 27 Output Voltage and Efficiency Test Setup.**

$$\text{Efficiency } \eta = \frac{V_o \cdot I_o}{V_{IN} \cdot I_{IN}} \times 100 \%$$



NOTE: All voltage measurements to be taken at the module terminals, as shown above. If sockets are used then Kelvin connections are required at the module terminals to avoid measurement errors due to socket contact resistance.

**Figure 26. Output Ripple and Noise Test Setup.**

## Design Considerations

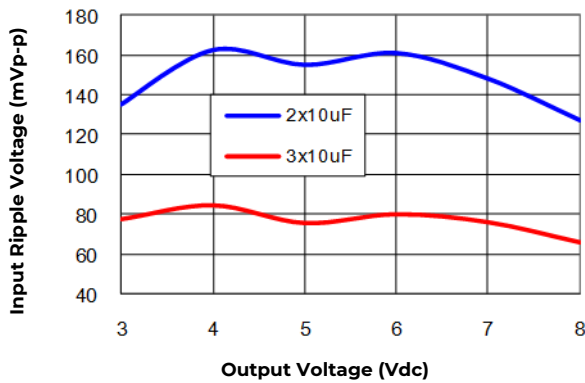
### Input Filtering

The 9-36V ProLynx module should be connected to a low ac-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pin of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 28 shows the input ripple voltage for various output voltages at maximum load current with  $2 \times 10 \mu F$  or  $3 \times 10 \mu F$  ceramic capacitors and an input of 12V while Fig. 29 shows the input ripple for an input voltage of 28V.

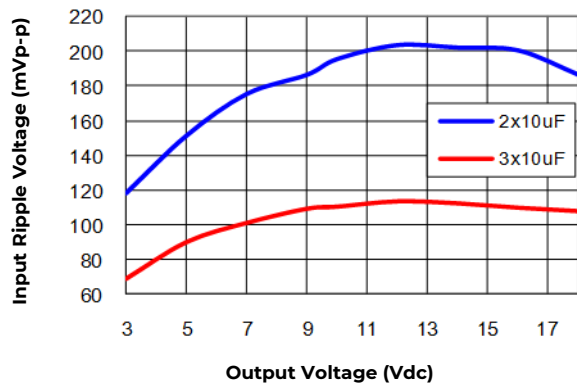


## Technical Specifications (continued)

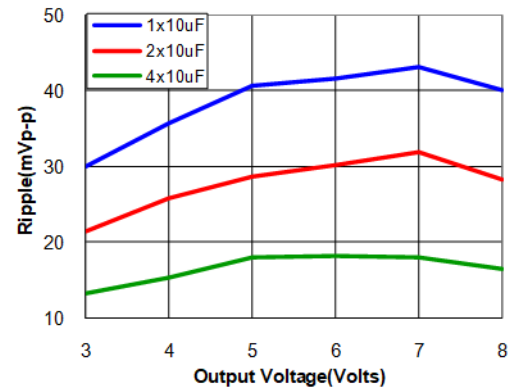


**Figure 28.** Input ripple voltage for various output voltages with 2x10 µF or 3x10 µF ceramic capacitors at the input (maximum load). Input voltage is 12V

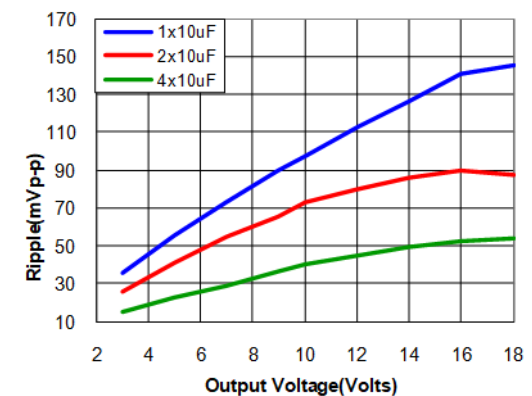
electrical specification table. Optimal performance of the module can be achieved by using the Tunable Loop™ feature described later in this data sheet.



**Figure 29.** Input ripple voltage for various output voltages with 2x10 µF or 3x10 µF ceramic capacitors at the input (maximum load). Input voltage is 28V



**Figure 30** Output ripple voltage for various output voltages with external 1x10 µF, 2x10 µF or 4x10 µF ceramic capacitors at the output (max load). Input voltage is 12V



**Figure 31** Output ripple voltage for various output voltages with external 1x10 µF, 2x10 µF or 4x10 µF ceramic capacitors at the output (max load). Input voltage is 28V

### Output Filtering

The 9-36V ProLynx modules are designed for low output ripple voltage and will meet the maximum output ripple specification with 0.1 µF ceramic and 10 µF ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module. Figures 30 and 31 provides output ripple information for different external capacitance values at various  $V_o$  and for full load currents. For stable operation of the module, limit the capacitance to less than the maximum output capacitance as specified in the

### Safety Considerations

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL ANSI/UL 62368-1 and CAN/CSA C22.2 No. 62368-1 Recognized, DIN VDE 0868-1/A11:2017 (EN62368-1:2014/A11:2017)

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV) or ES1, the input must meet SELV/ES1 requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

The input to these units is to be provided with a fast-acting fuse with a maximum rating of 8A in the positive input lead.

# Technical Specifications (continued)

## Feature Descriptions

### Remote Enable

The 9-36V ProLynx modules feature an On/Off pin for remote On/Off operation. Two On/Off logic options are available. In the Positive Logic On/Off option, (device code suffix “4” – see Ordering Information), the module turns ON during a logic High on the On/Off pin and turns OFF during a logic Low. With the Negative Logic On/Off option, (no device code suffix, see Ordering Information), the module turns OFF during logic High and ON during logic Low. The On/Off signal is always referenced to ground.

For positive logic modules, the circuit configuration for using the On/Off pin is shown in Figure 32. When the external transistor Q1 is in the OFF state, the ON/OFF pin is pulled high and transistor Q2 is OFF leading to Q3 also being OFF which turns the module ON. The external resistor  $R_{pullup}$  (100k recommended) must be sized so that  $V_{ON/OFF}$  is never more than 12V when Q1 is OFF. In particular, if  $V_{pullup}$  is made the same as the input voltage  $V_{in}$ , the resistor  $R_{pullup}$  must be large enough so that  $V_{ON/OFF}$  is never more than 12V. If the On/Off pin is left floating the module will be in the ON state.

For negative logic On/Off modules, the circuit configuration is shown in Fig. 33. When the external transistor Q1 is in the ON state, the ON/OFF pin is pulled low causing transistor Q2 to be OFF and the module to be turned ON. To turn the module OFF, Q1 is turned OFF, causing the ON/OFF pin to be pulled high turning Q2 ON and the module to be turned OFF.

**Leaving the On/Off pin floating will leave the module in an OFF state.**

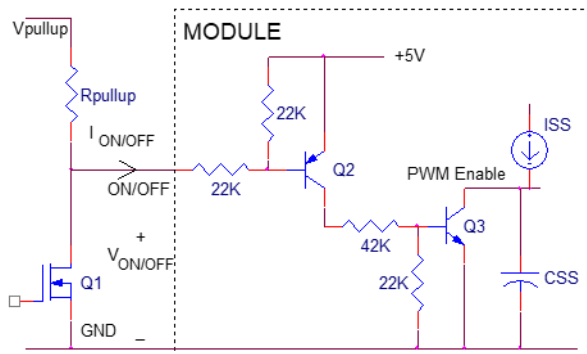


Figure 32. Circuit configuration for using positive On/Off logic.

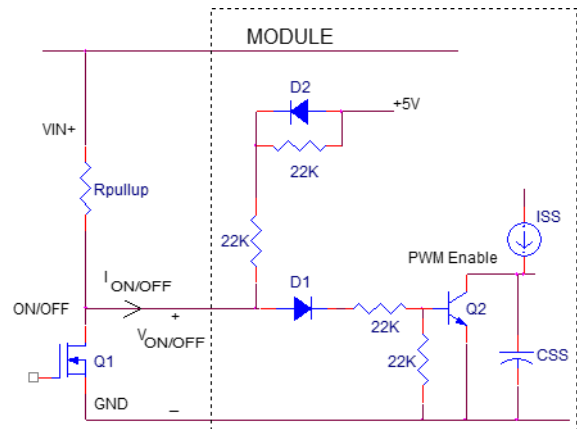


Figure 33. Circuit configuration for using negative On/Off logic.

### Overcurrent Protection

To provide protection in a fault (output overload) condition, the unit is equipped with internal current limiting circuitry and can endure current limiting continuously. At the point of current-limit inception, the unit enters hiccup mode. The unit operates normally once the output current is brought back into its specified range. The 9-36V ProLynx modules employ an innovative, patent pending, ‘AutoLimit’ capability. This results in automatic scaling of current limit with output voltage through an inverse relationship of the current limit threshold with the output voltage. This feature shown graphically in Fig. 34, allows higher output currents to be drawn from the module at lower output voltages thereby optimizing the power delivery capability of the module.

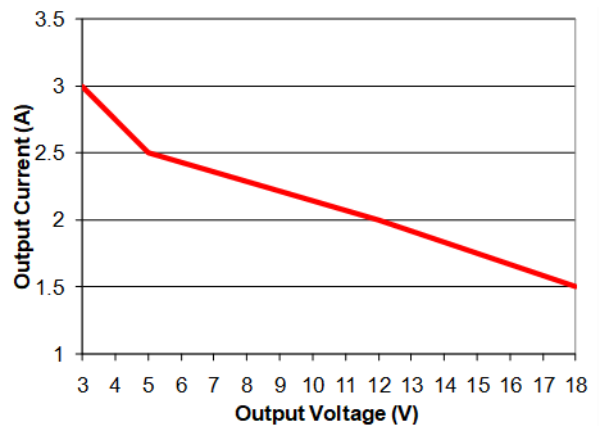


Figure 34. Graph showing maximum output current capability at different output voltages.

## Technical Specifications (continued)

### Over Temperature Protection

To provide protection in a fault condition, the unit is equipped with a thermal shutdown circuit. The unit will shutdown if the overtemperature threshold of 130°C is exceeded at the thermal reference point  $T_{ref}$ . The thermal shutdown is not intended as a guarantee that the unit will survive temperatures beyond its rating. Once the unit goes into thermal shutdown it will then wait to cool before attempting to restart.

### Input Undervoltage Lockout

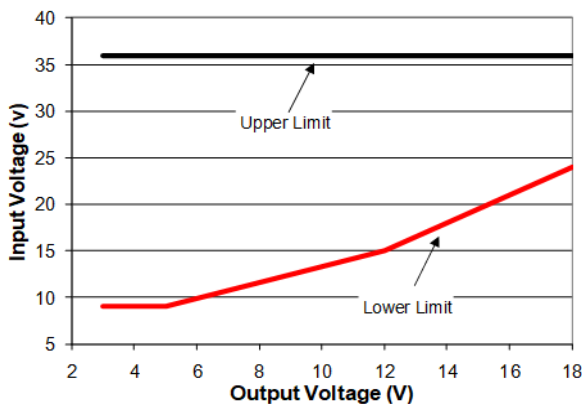
At input voltages below the input undervoltage lockout limit, the module operation is disabled. The module will begin to operate at an input voltage above the under voltage lockout turn-on threshold.

### Output Voltage Programming

The output voltage of the 9-36V ProLynx module can be programmed to any voltage from 3Vdc to 18Vdc by connecting a resistor between the Trim and GND pins of the module. Certain restrictions apply on the output voltage set point depending on the input voltage. These are shown in the Output Voltage vs. Input Voltage Set Point Area plot in Fig. 35. Without an external resistor between Trim and GND pins, the output of the module will be 0.7Vdc. To calculate the value of the trim resistor,  $R_{trim}$  for a desired output voltage, use the following equation:

$$R_{trim} = \left[ \frac{70}{(V_o - 0.7)} \right] k\Omega$$

$R_{trim}$  is the external resistor in  $k\Omega$ , and  $V_o$  is the desired output voltage.



**Figure 35. Output Voltage vs. Input Voltage Set Point Area plot showing limits where the output voltage can be set for different input voltages.**

Table 1 provides  $R_{trim}$  values required for some common output voltages.

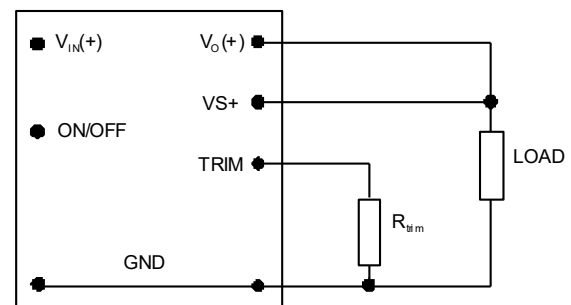
**Table 1**

$V_{o, set}$ (V)	$R_{trim}$ (K $\Omega$ )
3.3	26.92
5	16.27
6	13.2
9	8.43
12	6.19
15	4.89
18	4.04

By using a  $\pm 0.5\%$  tolerance trim resistor with a TC of  $\pm 100$ ppm, a set point tolerance of  $\pm 1.5\%$  can be achieved as specified in the electrical specification.

### Remote Sense

The 9-36V ProLynx power modules have a Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the VS+ and Vo pin. The voltage between the VS+ pin and Vo pin will not exceed 0.5V.



**Figure 36. Circuit configuration for programming output voltage using an external resistor.**

### Voltage Margining

Output voltage margining can be implemented in the 9-36V ProLynx modules by connecting a resistor,  $R_{margin-up}$ , from the Trim pin to the ground pin for margining-up the output voltage and by connecting a resistor,  $R_{margin-down}$ , from the Trim pin to output pin for margining-down. Figure 37 shows the circuit configuration for output voltage margining. The Lynx Programming Tool, available at [omnionpower.com](http://omnionpower.com)

under the Design Tools section, also calculates the values of  $R_{margin-up}$  and  $R_{margin-down}$  for a specific output voltage and % margin. Please consult your local OmniOn Power™ technical representative for additional details.

## Technical Specifications (continued)

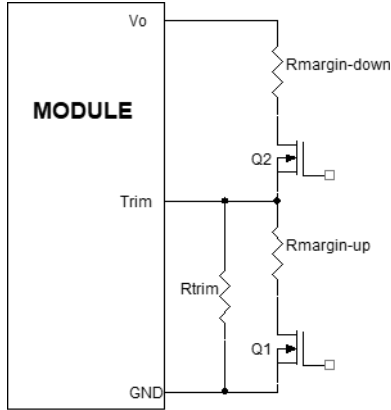


Figure 37. Circuit Configuration for margining Output voltage

### Tunable Loop™

The 9-36V ProLynx modules have a new feature that optimizes transient response of the module called Tunable Loop™.

External capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise (see Figures 30 and 31) and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable.

The Tunable Loop™ allows the user to externally adjust the voltage control loop to match the filter network connected to the output of the module. The Tunable Loop™ is implemented by connecting a series R-C between the VS+ and TRIM pins of the module, as shown in Fig. 38. This R-C allows the user to externally adjust the voltage loop feedback compensation of the module.

Recommended values of  $R_{TUNE}$  and  $C_{TUNE}$  for different output capacitor combinations are given in Tables 2, 3 and 4. Tables 2 and 3 show recommended values of  $R_{TUNE}$  and  $C_{TUNE}$  for different values of ceramic output capacitors up to 100 $\mu$ F that might be needed for an application to meet output ripple and noise requirements. Selecting  $R_{TUNE}$  and  $C_{TUNE}$  according to Tables 2 and 3 will ensure stable operation of the module

In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 4 lists recommended values of  $R_{TUNE}$  and  $C_{TUNE}$  in order to meet 2% output voltage deviation limits for some

common output voltages in the presence of a 50% of full load step change with an input voltage of 12 or 28V.

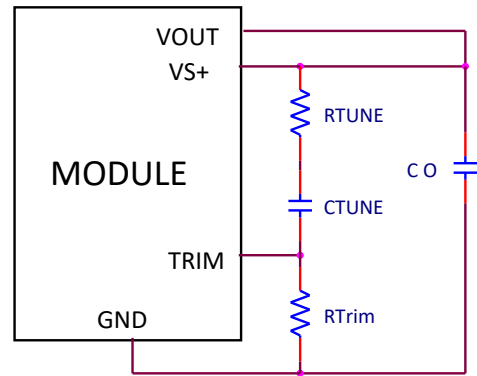


Figure 38. Circuit diagram showing connection of  $R_{TUNE}$  and  $C_{TUNE}$  to tune the control loop of the module.

Please contact your OmniOn Power™ technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external R-C to tune the module for best transient performance and stable operation for other output capacitance values or input voltages other than 12V/28V.

Table 2. General recommended values of  $R_{TUNE}$  and  $C_{TUNE}$  for  $V_{in}=12V$  and various external ceramic capacitor combinations.

$V_o=5V$

Table 3. General recommended values of  $R_{TUNE}$  and  $C_{TUNE}$  for

$C_o$	1x10 $\mu$ F	1x22 $\mu$ F	2x22 $\mu$ F	4x22 $\mu$ F	6x22 $\mu$ F
$R_{TUNE}$	330	270	220	180	180
$C_{TUNE}$	330pF	680pF	1500pF	2700pF	3300pF

$V_{in}=28V$  and various external ceramic capacitor combinations.

$V_o=5V$

$V_o=12V$

$C_o$	1x10 $\mu$ F	1x22 $\mu$ F	2x22 $\mu$ F	4x22 $\mu$ F	6x22 $\mu$ F
$R_{TUNE}$	Open	330	270	220	180
$C_{TUNE}$	Open	150pF	470pF	1000pF	1500p

Table 4. Recommended values of  $R_{TUNE}$  and  $C_{TUNE}$  to obtain

$C_o$	1x10 $\mu$ F	1x22 $\mu$ F	2x22 $\mu$ F	4x22 $\mu$ F	6x22 $\mu$ F
$R_{TUNE}$	Open	330	270	270	220
$C_{TUNE}$	Open	220p	330p	680p	1200p

transient deviation of 2% of  $V_{out}$  for a 50% of full load step

$V_{in}$	12V		28V			
$V_o$	3.3V	5V	3.3V	5V	12V	18V
$\Delta I$	1.5A	1.25A	1.5A	1.25A	1A	0.75A
$C_o$	1x330 $\mu$ F	1x330 $\mu$ F	1x330 $\mu$ F	1x330 $\mu$ F	2x22 $\mu$ F	1x22 $\mu$ F
	OsCon	OsCon	OsCon	OsCon		
$R_{TUNE}$	220	220	270	270	330	Open
$C_{TUNE}$	15nF	15nF	5600pF	5600pF	47pF	Open
$\Delta V$	26mV	22mV	24mV	20mV	223mV	193mV

## Technical Specifications (continued)

### Thermal Considerations

Power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 39. The preferred airflow direction for the module is in Figure 40. The derating data applies to airflow in either direction of the module's short axis.

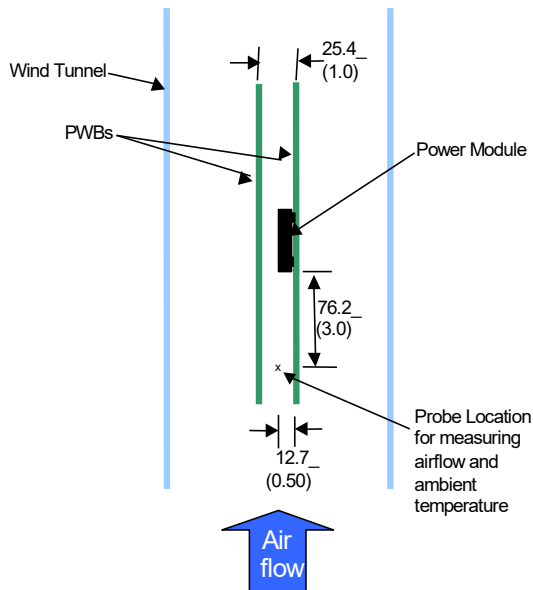


Figure 39. Thermal Test Setup.

The thermal reference points,  $T_{ref}$  used in the specifications are also shown in Figure 40. For reliable operation the temperatures at these points should not exceed 130°C. The output power of the module should not exceed the rated power of the module ( $V_{o,set} \times I_{o,max}$ ).

Please refer to the Application Note “Thermal Characterization Process For Open-Frame Board-Mounted Power Modules” for a detailed discussion of thermal aspects including maximum device temperatures.

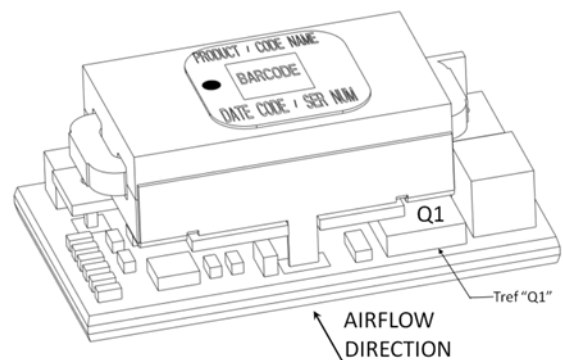


Figure 40. Preferred airflow direction and location of hot-spot of the module ( $T_{ref}$ ).

## Technical Specifications (continued)

### Shock and Vibration

The APXW003 modules are designed to withstand elevated levels of shock and vibration to be able to operate in harsh environments. The ruggedized modules have been successfully tested to the following conditions:

#### Non operating random vibration:

Random vibration tests conducted at 25°C, 10 to 2000Hz, for 30 minutes each level, starting from 30Grms (Z axis) and up to 50Grms (Z axis). The units were then subjected to two more tests of 50Grms at 30 minutes each for a total of 90 minutes.

#### Operating shock to 40G per Mil Std. 810G, Method 516.4 Procedure I:

The modules were tested in opposing directions along each of three orthogonal axes, with waveform and amplitude of the shock impulse characteristics as follows:

All shocks were half sine pulses, 11 milliseconds (ms) in duration in all 3 axes.

Units were tested to the Functional Shock Test of MIL-STD-810, Method 516.4, Procedure I - Figure 516.4-4. A shock magnitude of 40G was utilized. The operational units were subjected to three shocks in each direction along three axes for a total of eighteen shocks.

#### Operating vibration per Mil Std 810G, Method 514.5 Procedure I:

The APXW003 modules are designed and tested to vibration levels as outlined in MIL-STD-810G, Method 514.5, and Procedure 1, using the Power Spectral Density (PSD) profiles as shown in Table 1 and Table 2 for all axes. Full compliance with performance specifications was required during the performance test. No damage was allowed to the module and full compliance to performance specifications was required when the endurance environment was removed. The module was tested per MIL-STD-810, Method 514.5, Procedure I, for functional (performance) and endurance random vibration using the performance and endurance levels shown in Table 5 and Table 6 for all axes. The performance test has been split, with one half accomplished before the endurance test and one half after the endurance test (in each axis). The duration of the performance test was at least 16 minutes total per axis and at least 120 minutes total per axis for the endurance test. The endurance test period was 2 hours minimum per axis.

**Table 5: Performance Vibration Qualification - All Axes**

Frequency (Hz)	PSD Level (G <sup>2</sup> /Hz)	Frequency (Hz)	PSD Level (G <sup>2</sup> /Hz)	Frequency (Hz)	PSD Level (G <sup>2</sup> /Hz)
10	1.14E-03	170	2.54E-03	690	1.03E-03
30	5.96E-03	230	3.70E-03	800	7.29E-03
40	9.53E-04	290	7.99E-04	890	1.00E-03
50	2.08E-03	340	1.12E-02	1070	2.67E-03
90	2.08E-03	370	1.12E-02	1240	1.08E-03
110	7.05E-04	430	8.84E-04	1550	2.54E-03
130	5.00E-03	490	1.54E-03	1780	2.88E-03
140	8.20E-04	560	5.62E-04	2000	5.62E-04

**Table 6: Endurance Vibration Qualification - All Axes**

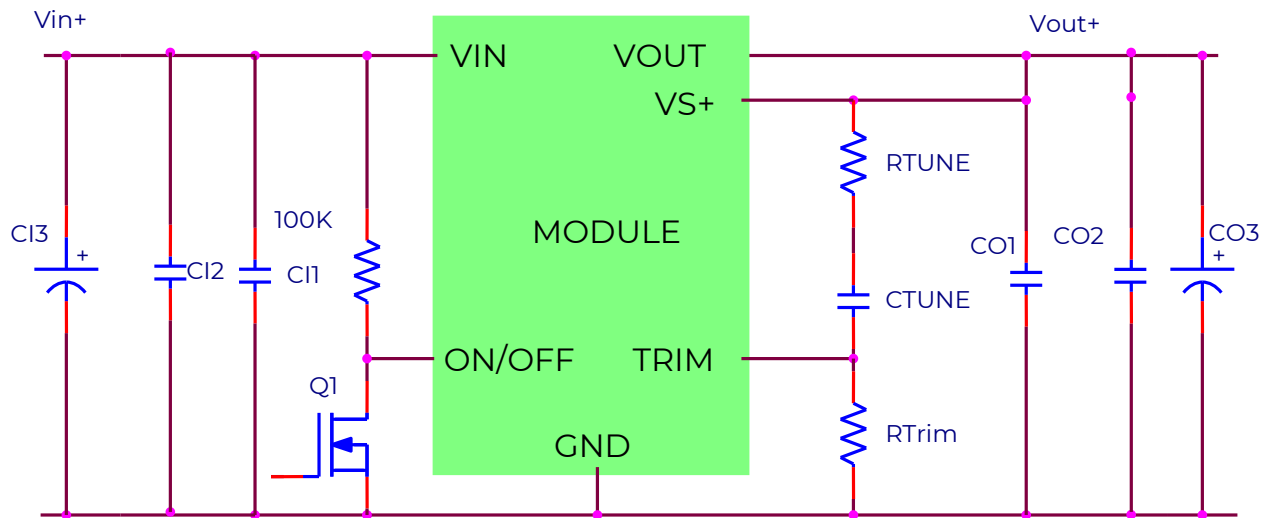
Frequency (Hz)	PSD Level (G <sup>2</sup> /Hz)	Frequency (Hz)	PSD Level (G <sup>2</sup> /Hz)	Frequency (Hz)	PSD Level (G <sup>2</sup> /Hz)
10	0.00803	170	0.01795	690	0.00727
30	0.04216	230	0.02616	800	0.05155
40	0.00674	290	0.00565	890	0.00709
50	0.01468	340	0.07901	1070	0.01887
90	0.01468	370	0.07901	1240	0.00764
110	0.00498	430	0.00625	1550	0.01795
130	0.03536	490	0.01086	1780	0.02035
140	0.0058	560	0.00398	2000	0.00398

## Technical Specifications (continued)

### Example Application Circuit

#### Requirements:

V <sub>in</sub> :	28V
V <sub>out</sub> :	12V
I <sub>out</sub> :	1.5A max., worst case load transient is from 1A to 1.5A
ΔV <sub>out</sub> :	1.5% of V <sub>out</sub> (180mV) for worst case load transient
V <sub>in</sub> , ripple	1.5% of V <sub>in</sub> (420mV, p-p)



C11	1 x 0.01μF/50V, 0603 ceramic capacitor
C12	2 x 10μF/50V ceramic capacitor (e.g. Murata GRM32ER71H106K)
C13	47μF/63V bulk electrolytic
CO1	1 x 0.01μF/25V, 0306 ceramic capacitor (e.g. Murata LLL185R71E103MA01L)
CO2	2 x 10μF/25V ceramic capacitor (e.g. Murata GCM32ER71E106KA42)
CO3	NA
CTune	47pF ceramic capacitor (can be 1206, 0805 or 0603 size)
RTune	332 ohms SMT resistor (can be 1206, 0805 or 0603 size)
RTrim	6.19kΩ resistor

# Technical Specifications (continued)

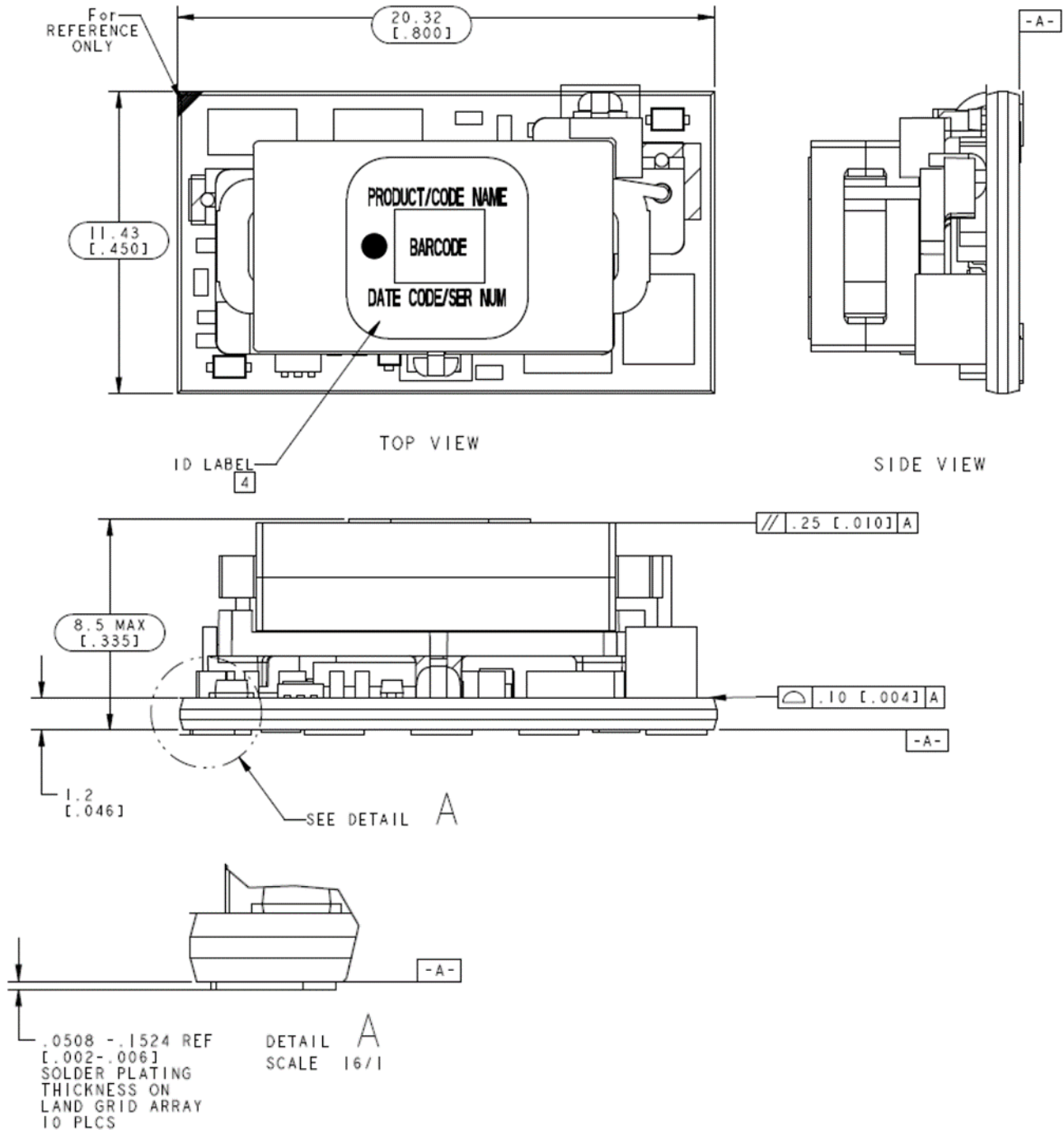
## Mechanical Outline

Dimensions are in millimeters and (inches).

Tolerances:  $x.x \text{ mm} \pm 0.5 \text{ mm}$  ( $x.xx \text{ in.} \pm 0.02 \text{ in.}$ ) [unless otherwise indicated]

$x.xx \text{ mm} \pm 0.25 \text{ mm}$  ( $x.xxx \text{ in.} \pm 0.010 \text{ in.}$ )

Angles  $\pm 2 \text{ Deg.}$





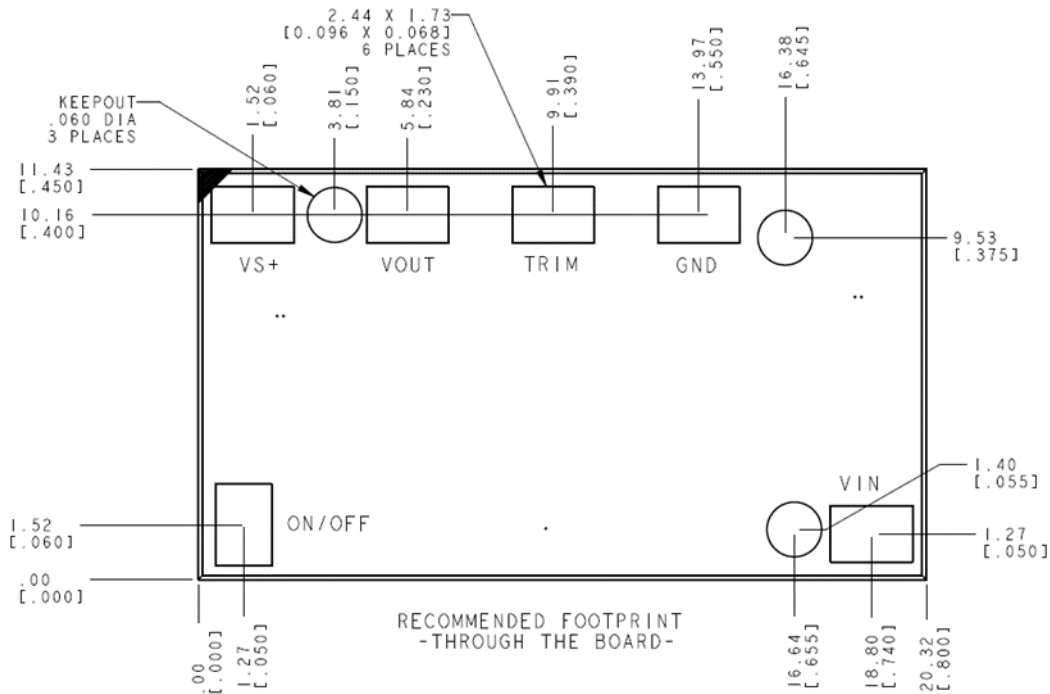
# Technical Specifications (continued)

## Recommended Pad Layout

Dimensions are in millimeters and (inches).

Tolerances: x.x mm ± 0.5 mm (x.xx in. ± 0.02 in.) [unless otherwise indicated]

x.xx mm ± 0.25 mm (x.xxx in ± 0.010 in.)



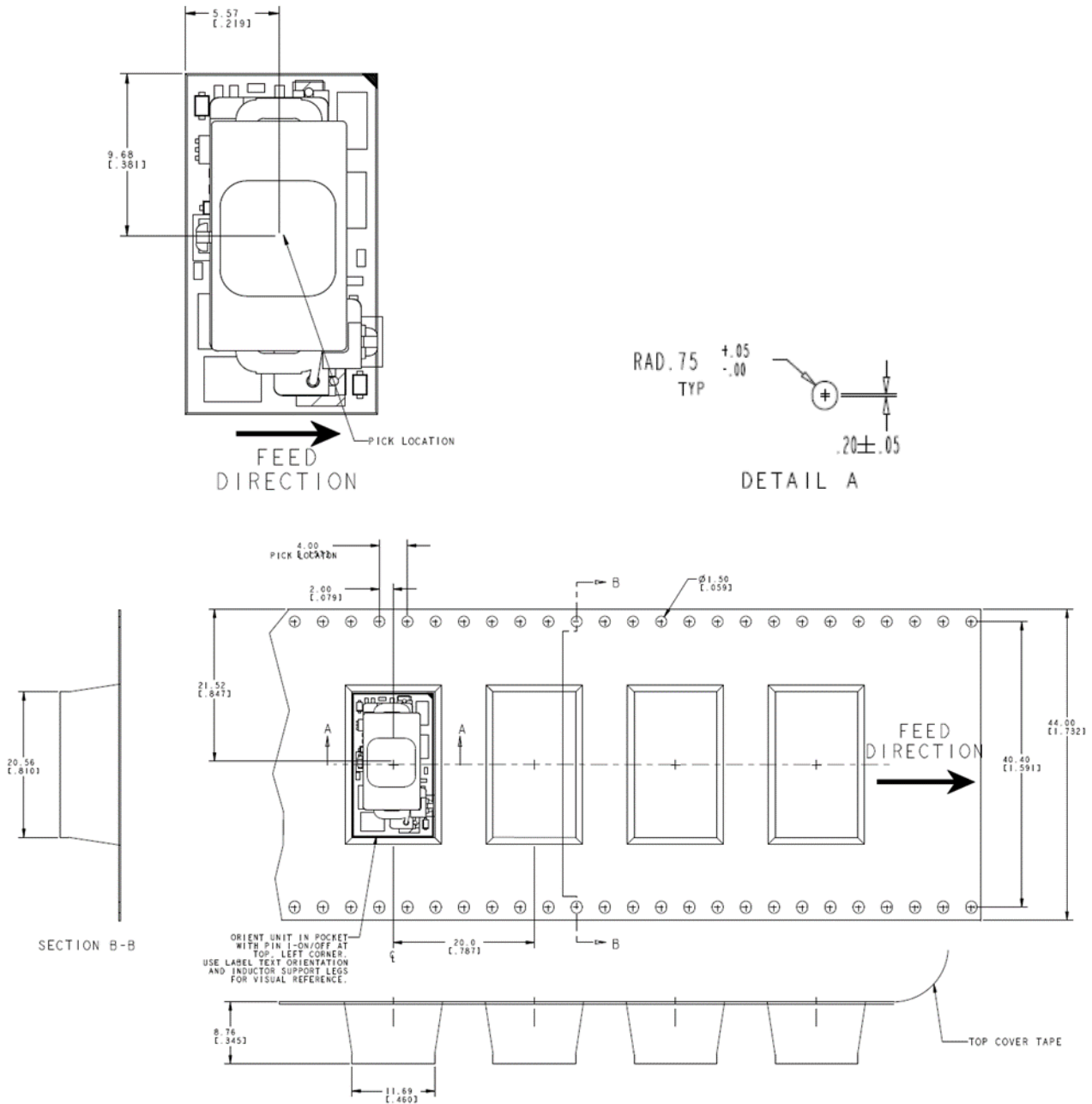
PIN	Pin	Description
1	ON/OFF	Remote On/Off control
2	Vin	Positive power input
3	GND	Common ground
4	TRIM	Output voltage programming
5	VOUT	Positive power output
6	VS+	Positive remote sense

# Technical Specifications (continued)

## Packaging Details

The 9-36V ProLynx modules are supplied in tape & reel as standard. Modules are shipped in quantities of 250 modules per reel.

All Dimensions are in millimeters and (in inches).



## Reel Dimensions:

- Outside Dimensions: 330.2 mm (13.00)
- Inside Dimensions: 177.8 mm (7.00")
- Tape Width: 44.00 mm (1.732")

## Technical Specifications (continued)

### Surface Mount Information

#### Pick and Place

The 9-36V ProLynx modules use an open frame construction and are designed for a fully automated assembly process. The modules are fitted with a label designed to provide a large surface area for pick and place operations. The label meets all the requirements for surface mount processing, as well as safety standards, and is able to withstand reflow temperatures of up to 300°C. The label also carries product information such as product code, serial number and the location of manufacture.

#### Nozzle Recommendations

The module weight has been kept to a minimum by using open frame construction. Variables such as nozzle size, tip style, vacuum pressure and placement speed should be considered to optimize this process. The minimum recommended inside nozzle diameter for reliable operation is 3mm. The maximum nozzle outer diameter, which will safely fit within the allowable component spacing, is 7 mm.

#### Bottom Side / First Side Assembly

This module is not recommended for assembly on the bottom side of a customer board. If such an assembly is attempted, components may fall off the module during the second reflow process.

#### Lead Free Soldering

The 9-36V ProLynx modules are lead-free (Pb-free) and RoHS compliant and fully compatible in a Pb-free soldering process. Failure to observe the instructions below may result in the failure of or cause damage to the modules and can adversely affect long-term reliability.

#### Pb-free Reflow Profile

Power Systems will comply with J-STD-020 Rev. C (Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices) for both Pb-free solder profiles and MSL classification procedures. This standard provides a recommended forced-air-convection reflow profile based on the volume and thickness of the package (table 4-2). The suggested Pb-free solder paste is Sn/Ag/Cu (SAC). The recommended linear reflow profile using Sn/Ag/Cu solder is shown in Fig. 41. Soldering outside of the recommended profile requires testing to verify results and performance. For questions regarding

Land grid array(LGA) soldering, solder volume; please contact OmniOn Power™ for special manufacturing process instructions.

#### MSL Rating

The 9-36V ProLynx modules have a MSL rating of 2a.

#### Storage and Handling

The recommended storage environment and handling procedures for moisture-sensitive surface mount packages is detailed in J-STD-033 Rev. A (Handling, Packing, Shipping and Use of Moisture/Reflow Sensitive Surface Mount Devices). Moisture barrier bags (MBB) with desiccant are required for MSL ratings of 2 or greater. These sealed packages should not be broken until time of use. Once the original package is broken, the floor life of the product at conditions of  $\leq 30^{\circ}\text{C}$  and 60% relative humidity varies according to the MSL rating (see J-STD-033A). The shelf life for dry packed SMT packages will be a minimum of 12 months from the bag seal date, when stored at the following conditions:  $< 40^{\circ}\text{C}$ ,  $< 90\%$  relative humidity.

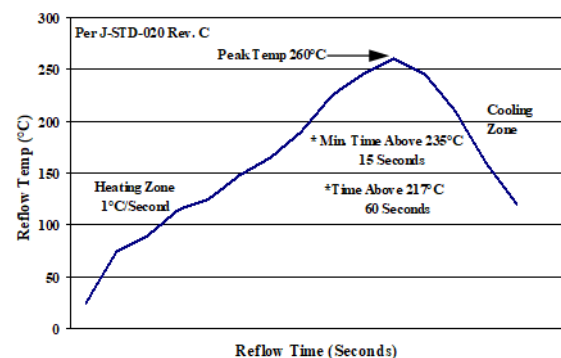


Figure 41. Recommended linear reflow profile using Sn/Ag/Cu solder.

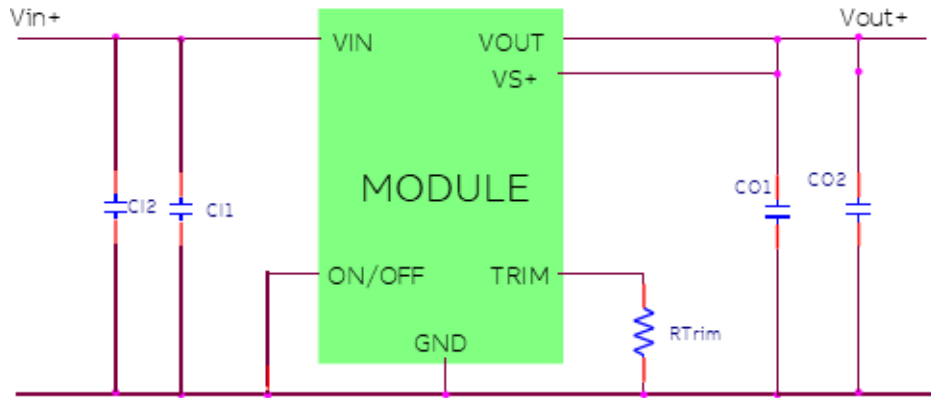
#### Post Solder Cleaning and Drying Considerations

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to Board Mounted Power Modules: Soldering and Cleaning Application Note (AN04-001).

## Technical Specifications (continued)

### EMC Considerations

The circuit and plots in Figure 42 shows a suggested configuration to meet the radiated emission limits of FCC Class A. Actual performance depends on layout and external components used.



C11	1 x 0.01 $\mu$ F/50V, 0603 ceramic capacitor
C12	2 x 10 $\mu$ F/50V ceramic capacitor (e.g. Murata GRM32ER71H106K)
CO1	1 x 0.01 $\mu$ F/25V, 0306 ceramic capacitor (e.g. Murata LLL185R71E103MA01L)
CO2	2 x 10 $\mu$ F/25V ceramic capacitor (e.g. Murata GCM32ER71E106KA42)
RTrim	6.19K $\Omega$ resistor

EUT: APXW003A0X3-SRZ / TEM Cell

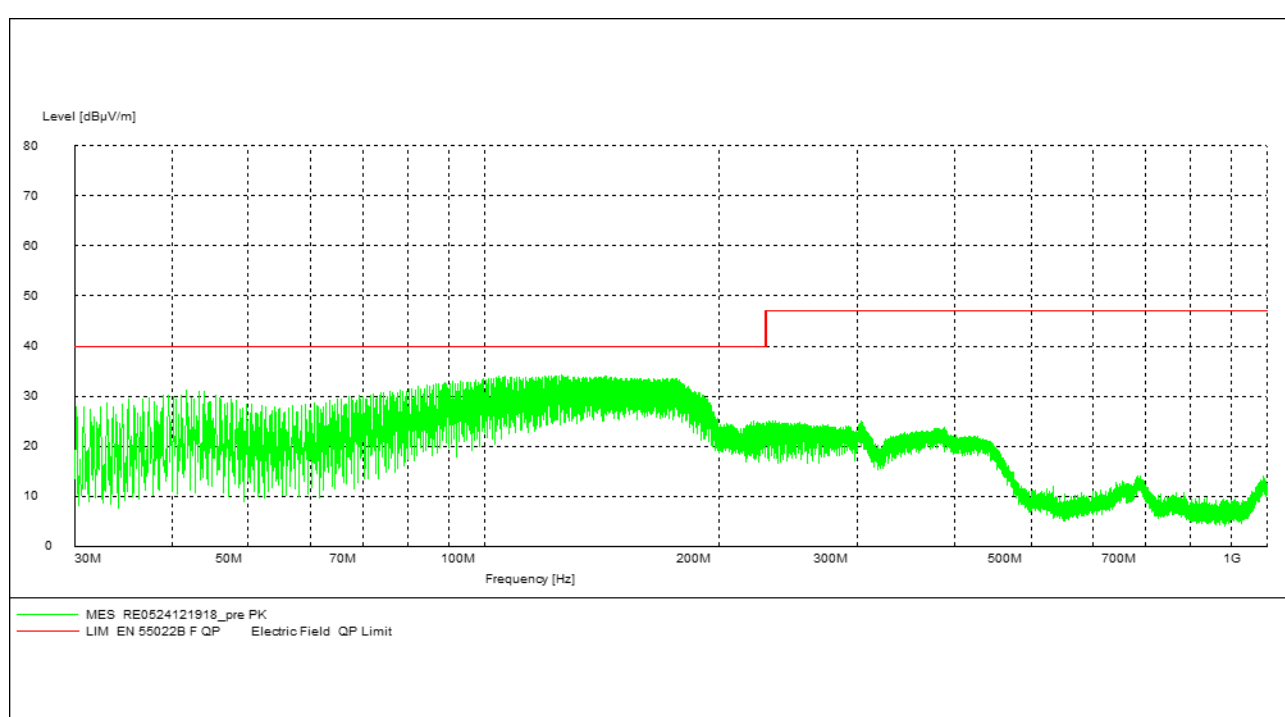


Fig 42 – EMI Plot of APXW003 on evaluation board with 12 V in @ 1.2 A in / 5 Vdc @ 2.5 A out

## Technical Specifications (continued)

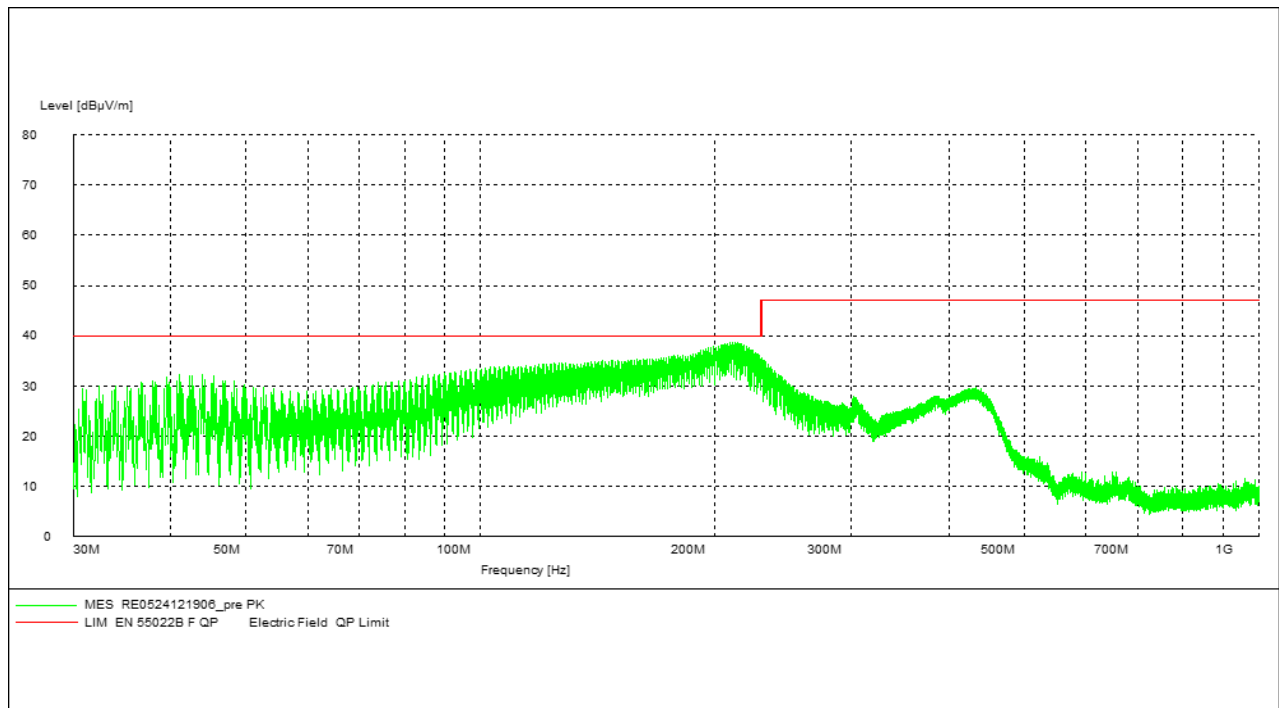


Fig 43 – EMI Plot of APXW003 on evaluation board with 24 V in @ 0.6 A in / 5 Vdc @ 2.5 A out

## Technical Specifications (continued)

### Ordering Information

Please contact your OmniOn Power™ Sales Representative for pricing, availability and optional features.

**Table 8. Device Codes**

Device Code	Input Voltage Range	Output Voltage	Output Current	On/Off Logic	Connector Type	Ordering Code
APXW003A0X3-SRZ	9 – 36Vdc	3 – 18Vdc	3A – 1.5A	Negative	SMT	CC109161238
APXW003A0X43-SRZ				Positive	SMT	CC109161246
APXW003A0X3-SRDZ				Negative	SMT	150026706

-Z refers to RoHS compliant parts

**Table 9. Coding Scheme**

TLynx family	Sequencing feature	Input voltage range	Output current	Output voltage	On/Off logic	Remote Sense	Options	ROHS Compliance	
AP	X	W	003	X	4	3	-SR	-D	Z
	X = w/o Seq.	W = 9-36V	3A	X = programmable output	4 = positive No entry = negative	Available	S = Surface Mount R = Tape & Reel	D = 105°C operating ambient, 40G operating shock as per MIL	Z = ROHS

## Change History (excludes grammar & clarifications)

Revision	Date	Description of the change
1.8	06/23/2022	Corrected typo in capacitor values
1.9	12/20/2023	Updated as per OmniOn template
2.0	05/29/2024	Trademark <sup>TM</sup> removed from ProLynx

## OmniOn Power Inc.

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[omnionpower.com](https://www.omnionpower.com)

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\* UL is a registered trademark of Underwriters Laboratories, Inc.

† CSA is a registered trademark of Canadian Standards Association.

‡ VDE is a trademark of Verband Deutscher Elektrotechniker e.V.

\*\* ISO is a registered trademark of the International Organization of Standards

<sup>1</sup> Depending on Input and Output Voltage, external capacitors require using the new Tunable Loop™ feature to ensure that the module is stable as well as getting the best transient response. See the Tunable Loop™ section for details.

\* Larger values may be possible at specific output voltages. Please consult your OmniOn Power™ Technical representative for additional details.

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